

Profibus DP Master to Crowcon Vortex Gas Analyser



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# **Document Revison History**

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## **Overview**

This document defines an interface between a Profibus master (PLC) and a Crowcon Vortex gas analyser. The Profibus master communicates with the Vortex (Modbus slave) using the HMS AnyBus Profibus-DP Serial Gateway device. The Anybus module acts as a protocol bridge between the Profibus master and the Vortex Modbus slave.

# Requirements

#### **HMS** equipment:

- 1 x Profibus slave module (AnyBus Profibus-DP Serial Gateway)
- 1 x GSD file for the AnyBus module (HMS\_1803.GSD).

This file can be downloaded from the following web page:

http://www.anybus.com/support/support.asp?PID=104&ProductType=Anybus%20Communicator

## **Crowcon equipment:**

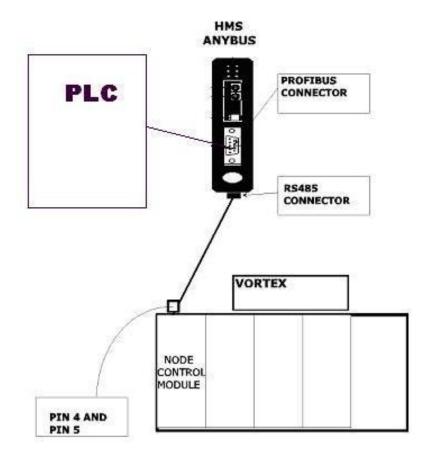
- 1 x Vortex Manual
- 1 x Crowcon Resource CD Vortex PC
- 1 Vortex gas analyser with the following hardware configuration:
  - 1 x Node Control Module
  - 3 x Quad Channel Module
- 12 x Ammonia sensor 0 1000 p.p.m.
  - 4 x Relay Module
  - 1 x Power Monitoring Module
  - 1 x 220 VOLTS AC converter

# **Configuration Layout**

The following picture shows how to attach the different components of the system.

## **AnyBus Layout**

The HMS AnyBus device is connected to the **Vortex Node Control Module** using the AnyBus RS485 connector (located at the bottom of the unit).



The next section explains exactly which PINs should be connected from the HMS AnyBus device to the Crowcon Vortex unit.

# **Hardware Settings**

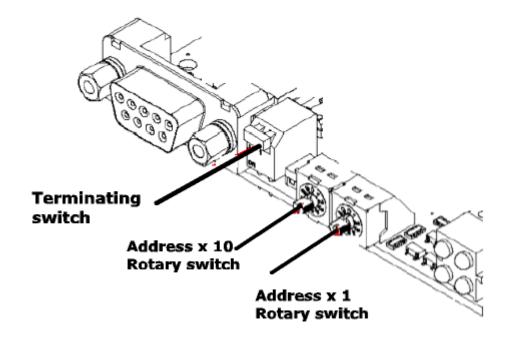
#### **AnyBus Module**

The AnyBus module acts as a protocol converter Profibus/Modbus and vice-versa. This device has been configured as a **Profibus slave** and as a **Modbus Master**.

#### Profibus address

In order to change the Profibus slave address open the AnyBus front case (Profibus side) and set the address using the two rotary switches accordingly.

For example, to set the AnyBus device as a Profibus slave address number 3, the **x 10 rotary switch** must be set to zero and the **x 1 rotary switch** must be set to 3.



Please consult the HMS documentation for further details (Technical documentation: HMS AnyBus-DP Serial Profibus Gateway section).

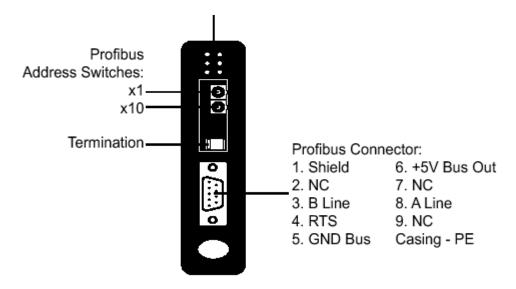
### Please note the initial Profibus address has been set to 77

#### Modbus address

The Modbus address that the AnyBus queries is Modbus address 1, so the Vortex unit has to be configured as slave address number 1.

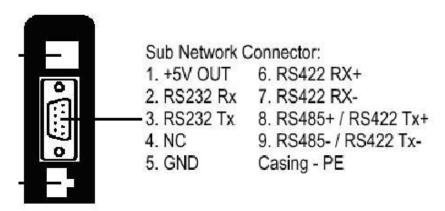
#### Connecting the AnyBus to the Profibus device

The AnyBus device should be connected to the PLC using a standard Profibus cable (straight serial cable male to male). The location of the Profibus connector is on the front side of the AnyBus module, where the LEDs are located:



#### Connecting the AnyBus to the Modbus device

The Modbus communication between the AnyBus and the Vortex is the RS485 2-wires physical interface. So we use the pins number 8 and 9 of the Dsub9. The Modbus connector is on the rear side of the AnyBus device.



The AnyBus female 9 way cannon "D" connector (Sub Network Connector) shown above should be connected to the Vortex Node Controller Module as follows:

ANYBUS CONNECTOR		VORTEX NODE CONTROLLER	
PIN 8 PIN 9		PIN 4 PIN 5	

Please read the Crowcon documentation for further details (Technical documentation: Vortex Unit section).

# **Hardware Configuration**

#### **Profibus Configuration**

In order to configure the AnyBus Profibus protocol, the PLC must be configured to use the ProfiBus communication (the AnyBus device as a Profibus slave).

Please refer to the PLC documentation in order to install and configure this device (Technical Documentation).

# **Profibus AnyBus Configuration**

Importing the GSD file

Import the file HMS\_1803.GSD to the PLC software (PLC configurator tool) in order to include the AnyBus as a Profibus slave in the Profibus network.

### Configuring the network

The AnyBus module can be found in the hardware PLC catalogue.

Please consult the HMS documentation for further details in order to connect the AnyBus device to a PLC Profibus bus (Technical documentation: AnyBus installation for PLC).

## **Modbus Configuration**

The Modbus units have to be configured as a slave address number 1 in order to be accessed properly by the AnyBus communicator.

Please consult the Crowcon documentation (Technical documentation: Vortex Unit section).

# **Software Configuration**

### **AnyBus Software Configuration**

#### **Overview**

Basically, the AnyBus device is a bridge between the Profibus protocol and the Modbus protocol.

The AnyBus has got three memory buffers:

- Input data: data that should be sent to the Profibus device (i.e. PLC).
- Output data: data received from the Profibus device.
- General data: data to perform internal calculations.

In this particular project, just only the first buffer is interesting. The PLC will read data from the Vortex unit but it not necessary to send anything from the PLC to the Vortex.

#### **ABC Config Tool**

The ABC Config tool is the HMS software that allows sending Modbus commands and mapping the response in the input data buffer.

This software can be downloaded from the following location:

http://www.anybus.com/upload/AnyBus%20Communicator-8255-ABC\_Setup\_2\_10.exe

Once the software has been installed, it is possible to communicate to the AnyBus device using the programming cable. Two things have to be configured: the Profibus protocol and the Modbus Protocol.

#### **Profibus Configuration**

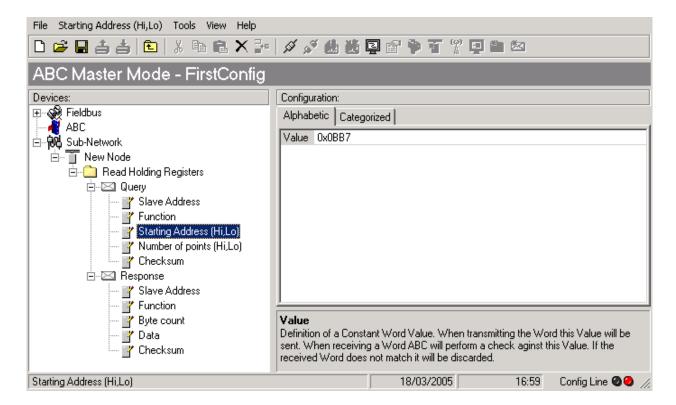
The AnyBus device will be automatically detected once the PLC software has imported the GSD file. Obviously, the AnyBus configuration switches for setting the Profibus address have to be set previously (see the Hardware Configuration section in this document).

### **Modbus Configuration**

Using the ABC Config Tool it is possible to send standard Modbus commands or to specify new ones. For clarity, this document describes only the Read Holding Registers.

To send a Modbus command is as easy as create new Read Holding Register object, which consist of a fully configurable Modbus query and a response.

The following picture shows a Read Holding Register object into the ABC Config Tool. The picture highlights the starting address of the Modbus packet, which is 0x0BB7.

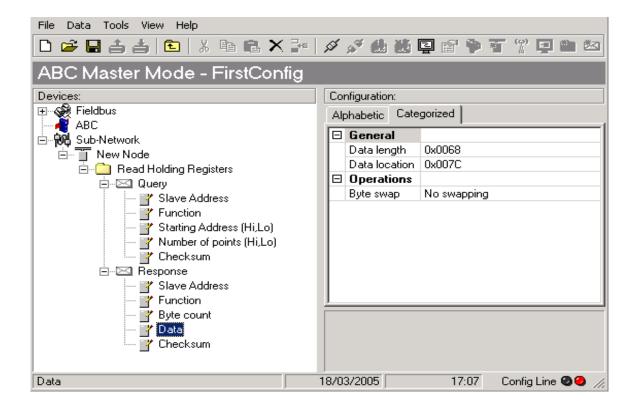


To change any other value, select the appropriate field and change the value accordingly.

#### **AnyBus Mapping**

The last thing to do is to map the Modbus data into the AnyBus input buffer in order to be consumed by the Profibus device. The Response Data property allows indicating where to map the value/values read from the Modbus response.

The following picture shows the values associated with the Data property. In this example, the Modbus payload has 0x0068 bytes and will be mapped in the input buffer starting at 0x007C address. So 0x0068 bytes will be available to be consumed by the PLC via the Profibus interface.



The application downloaded into the AnyBus can be modified importing the source code called 'Vortex\_Final.cfg' via the File → Open menu.

### **PLC Configuration**

The AnyBus device sends 228 bytes from the Modbus device (Vortex) to the Profibus bus. Only a subset of this data is interesting for the project. The following table shows the starting address and description of the Profibus set of data that the PLC must read:

#### **PROFIBUS MAPPING**

TROTIBOO MALTINO				
WORD	BYT	E INFORMATION		
	0	0 SYSTEM STATUS		
	1	2 POWER STATUS		
	2	4 CHANNEL 1 ANALOGUE		
	3	6 CHANNEL 1 STATUS		
	4	8 XXX		
	5	10 XXX		
	6	12 XXX		
	7	14 XXX		
	8	16 XXX		
	9	18 XXX		
	10	20 XXX		
	11	22 XXX		
	12	24 CHANNEL 2 ANALOGUE		
	13	26 CHANNEL 2 STATUS		
	14	28 XXX		
	15	30 XXX		
	16	32 XXX		
	17	34 XXX		
	18	36 XXX		
	19	38 XXX		
	20	40 XXX		
	21	42 XXX		
	22	44 CHANNEL 3 ANALOGUE		
	23	46 CHANNEL 3 STATUS		
	23			
•••	32	 64 CHANNEL 4 ANALOGUE		
	33	66 CHANNEL 4 STATUS		
	33	00 CHANNEL 4 STATUS		
•••	 42	 84 CHANNEL 5 ANALOGUE		
	43			
	43	80 CHANNEL 3 STATUS		
•••	 52	104 CHANNEL 6 ANALOGUE		
	53	106 CHANNEL 6 STATUS		
	55	100 CHANNEL 0 STATUS		
•••	62	124 CHANNEL 7 ANALOGUE		
	63	126 CHANNEL 7 STATUS		
		120 CHANNEL / STATUS		
•••	72	144 CHANNEL 8 ANALOGUE		
	72 73	146 CHANNEL 8 STATUS		
•••	82	 164 CHANNEL 9 ANALOGUE		
	83	166 CHANNEL 9 STATUS		
•••	92	184 CHANNEL 10 ANALOGUE		
	93			
•••	102	204 CHANNEL 11 ANALOGUE		
		206 CHANNEL 11 STATUS		
	112	224 CHANNEL 12 ANALOGUE		
	113	226 CHANNEL 12 STATUS		

The structure of each of the words is as follows:

#### System Status

This occurs once for each Vortex unit. The System Status has been mapped at word address number 0 as you can see in the previous table.

The system status is a 16-bit bitmap and the following table identifies the meaning of each bit. A bit set to logic 1 indicates that the defined condition is present.

```
System status

Bitmap, where the bits are defined as follows:

0 ⇒ Channel Test Mode active

1 ⇒ Jump/Hold Mode active

2 ⇒ System fault

3 ⇒ System fault is Battery fault

4 ⇒ System fault is FRAM Data Integrity fault

5 ⇒ System fault is Internal I2C Bus fault

6 ⇒ System fault is Display Access fault

7 ⇒ System fault is Power Monitor Access fault

8 ⇒ System fault is External I2C Bus fault

9 ⇒ System fault is Relay Board fault

10-15 are unused.
```

### **Power Status**

This occurs once for each Vortex Unit. The Power Status has been mapped at word address number 1.

The following table explains the different values that can be read:

Power status	Integer, where the values are defined as follows:
1 word	0 OK 1 Mains OK Battery LOW 2 Mains FAIL Battery GOOD 3 Mains OK Battery DISCONNECTED 4 Mains FAIL Battery LOW 5 No communications to Power Card

#### Channel analogue and channel status

The channel analogue contains the current value of the transducer and the channel status is a bitmap indicating various states of the channel.

There is one channel analogue word and one channel status word for each of the different channels. The channel analogue and the channel status are consecutive words in the Profibus mapping.

The following table indicates in detail the value represented by the channel analogue word and the channel status word. A bit set to logic 1 indicates that the defined condition is present.

Channel analogue	Integer between 0 and 1000.
1 word	The current reading on the detector.
Channel status	Bitmap, where the bits are defined as follows:
1 word	<pre>0 ⇒ Alarm 1 trigger condition present 1 ⇒ Alarm 2 trigger condition present 2 ⇒ Alarm 3 trigger condition present 3 ⇒ Detector level interpreted as inhibit 4 ⇒ Detector level interpreted as Low Info 5 ⇒ Detector level interpreted as High Info 6 ⇒ Low End fault 7 ⇒ High End fault 8 ⇒ Detector I2C fault 9 ⇒ Detector inhibited</pre> 10-15 are unused.

The channel status indicates whether an alarm trigger condition is present (bits 0, 1 and 2 in the bitmap), whether there is a fault condition present (bits 6,7 and 8 in the bitmap) or whether the channel has been inhibited or not (bit 9 in the bitmap).

#### **Technical documentation**

In order to know in more detail how to configure the different modules of this project please refer to the following documentation:

#### **Crowcon Vortex Unit**

#### **Vortex Configuration**

Vortex 12 Channel Gas and Fire Control Panel, Crowcon Detection instruments Ltd.

This document is already included with the hardware.

# **HMS AnyBus Profibus-DP Serial Gateway**

#### **GSD-File**

GSD-File for AnyBus Profibus Serial Gateway, HMS Industrial networks

This file can be downloaded from the following web page:

http://www.anybus.com/support/support.asp?PID=104&ProductType=AnyBus%20Communicator

## **Installation Leaflet**

Installation Guide, HMS Industrial Networks

This leaflet can be downloaded from the following web page:

http://www.anybus.com/support/support.asp?PID=104&ProductType=AnyBus%20Communicator